

FIG. 1

SCENE CHANGE DETECTION

COMPARE LENGTHS OF
dct_dc_size VARIABLE LENGTH
CODES TO AT LEAST ONE LENGTH
THRESHOLD TO DETECT EDGES

APPLY THINNING FILTER COMPARING
LENGTHS OF dct_dc_size VARIABLE
LENGTH CODES TO FIND MOST
SIGNIFICANT EDGES

COMPUTE AUTO-COINCIDENCE COUNTS C_{cc}
AND C_{pp} OF MOST SIGNIFICANT EDGES IN THE
CURRENT AND PRIOR FRAMES RESPECTIVELY

COMPUTE CROSS-COINCIDENCE COUNT
(C_{cp}) OF MOST SIGNIFICANT EDGES IN CURRENT
FRAME AND PRIOR FRAME

COMPUTE COINCIDENCE COEFFICIENT

$$R = 2C_{cp} / (C_{cc} + C_{pp})$$

COMPARE COINCIDENCE COEFFICIENT
TO AT LEAST ONE COINCIDENCE THRESHOLD
TO DETECT A SCENE CHANGE

END

FIG. 2

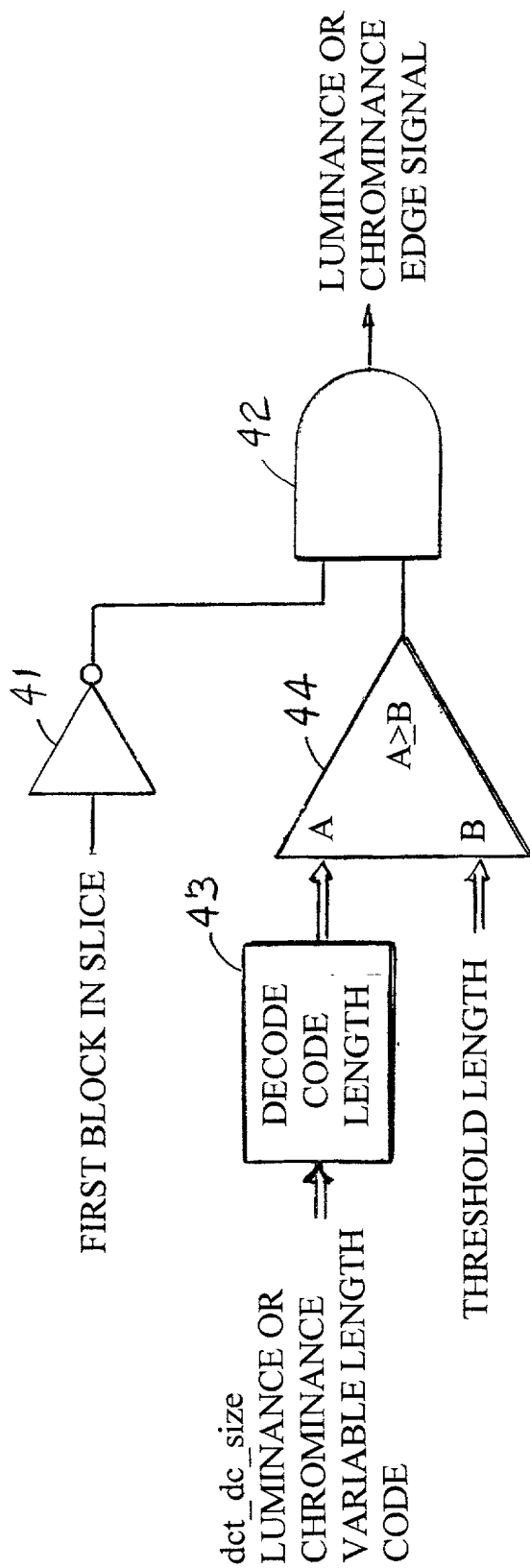
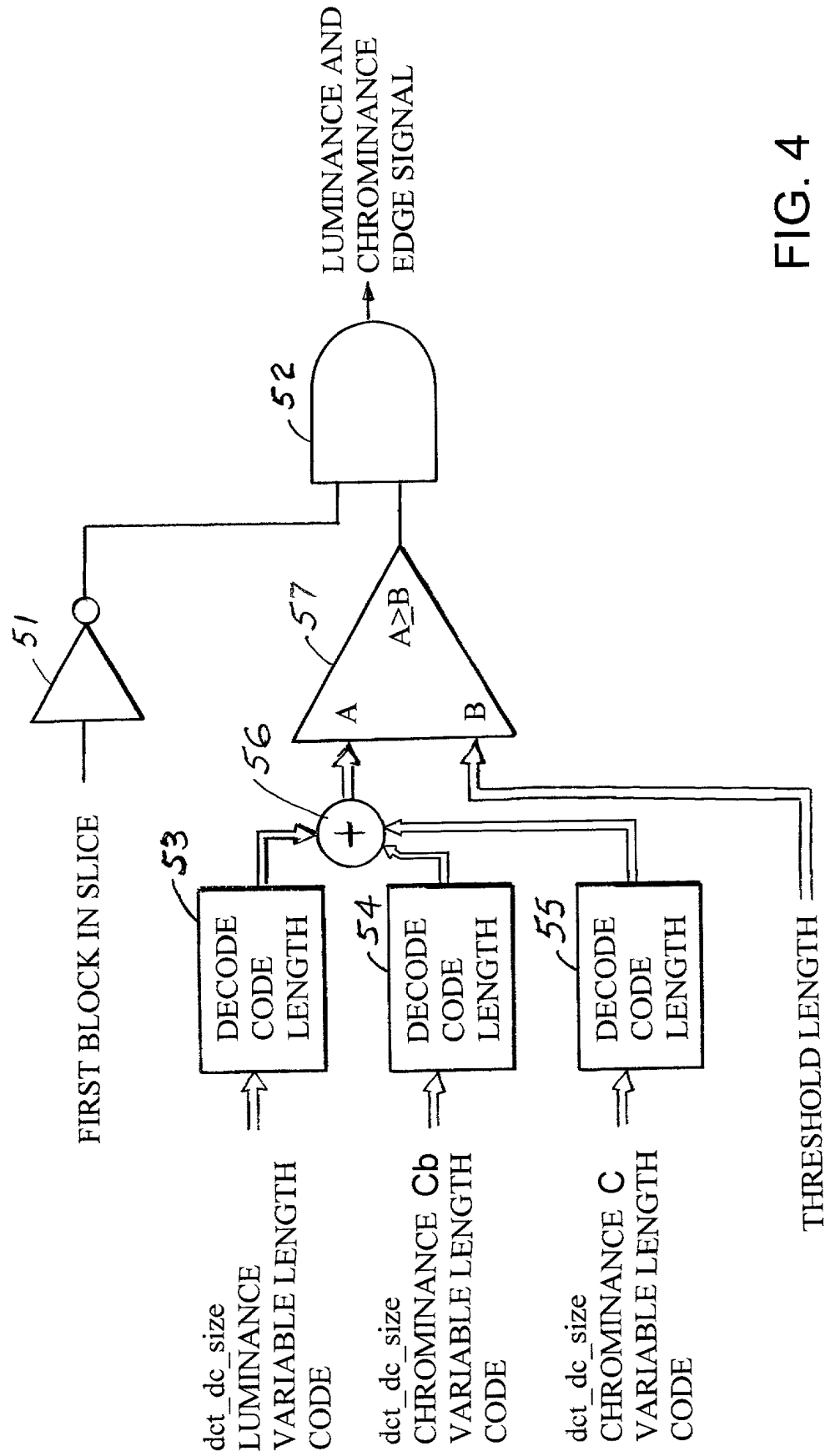


FIG. 3



TOP SECRET

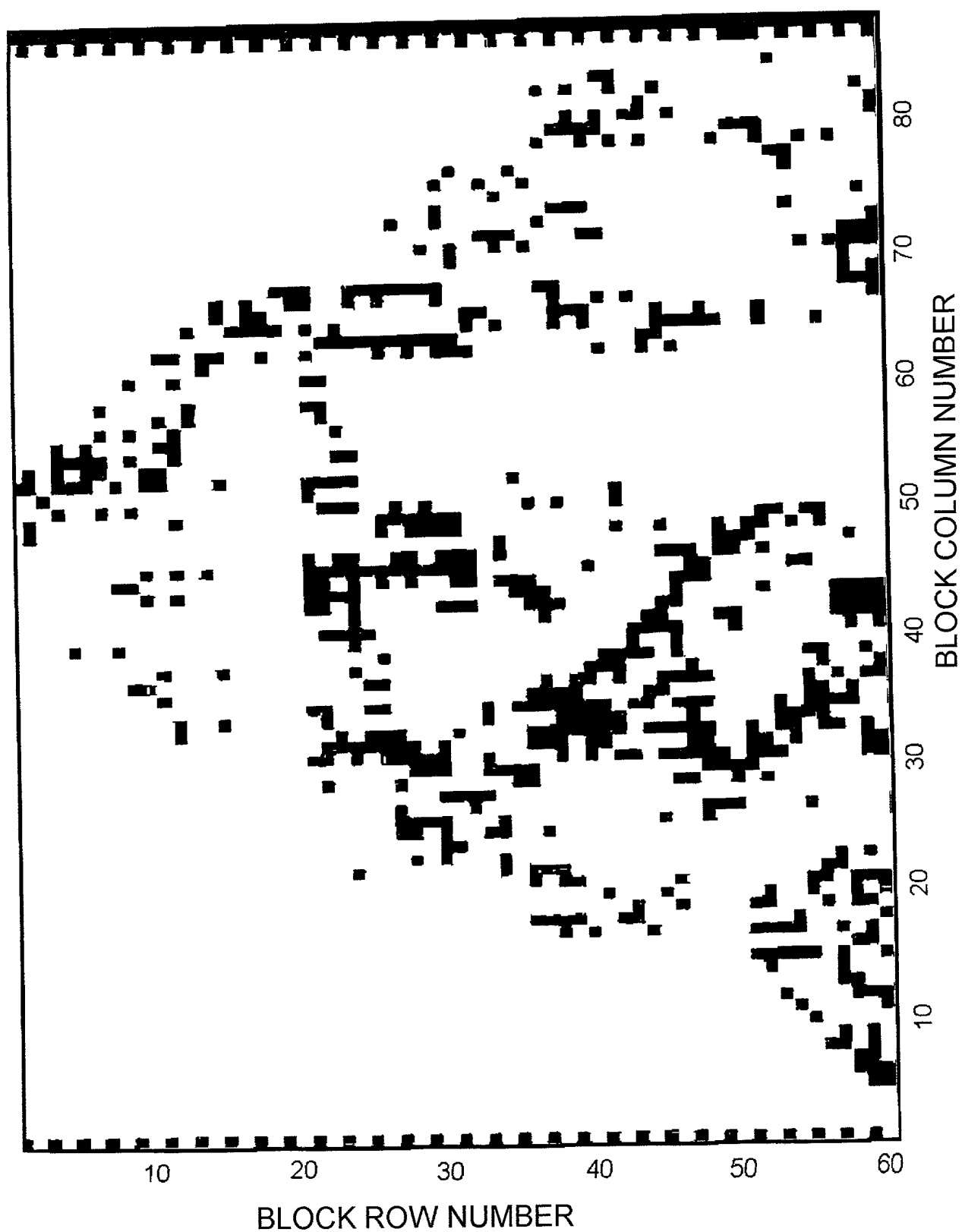


FIG. 5

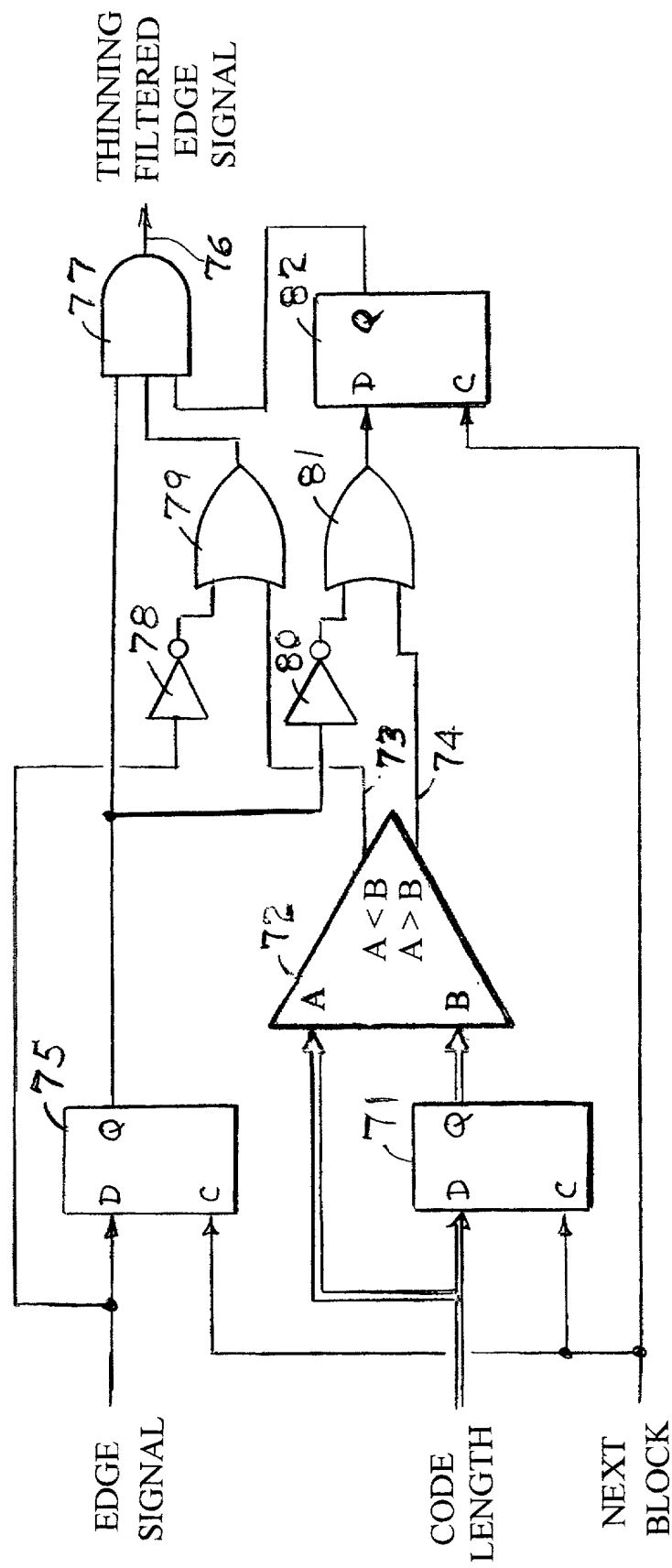


FIG. 6

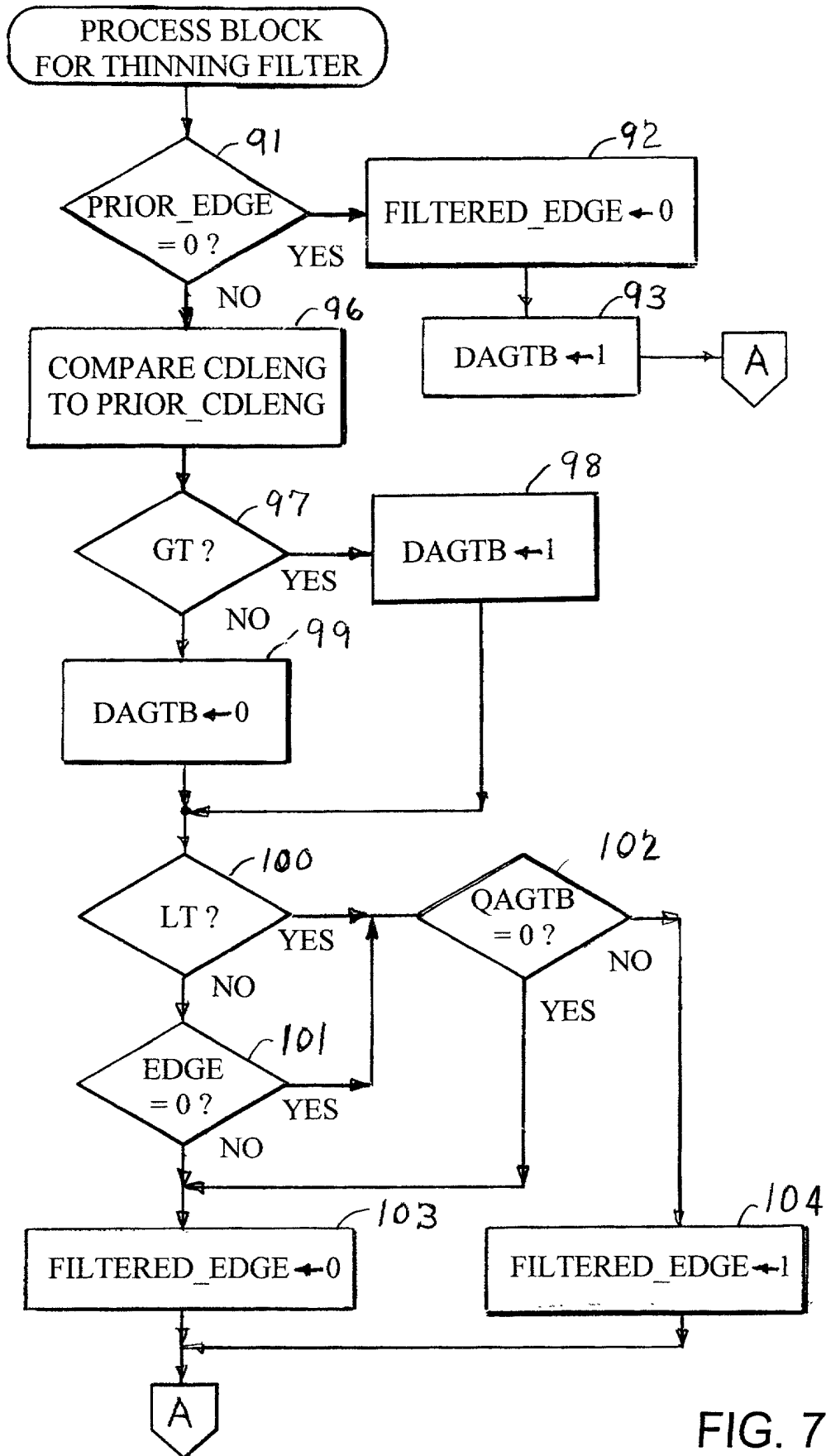


FIG. 7

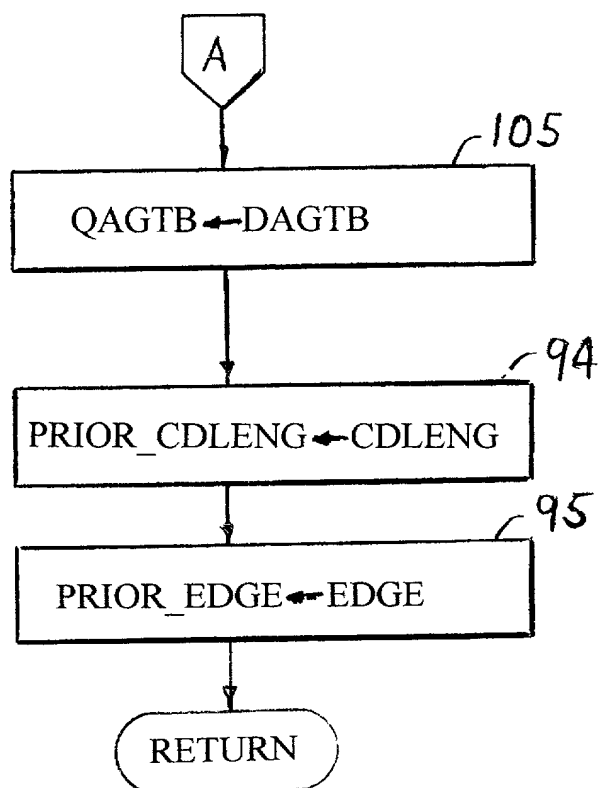


FIG. 8

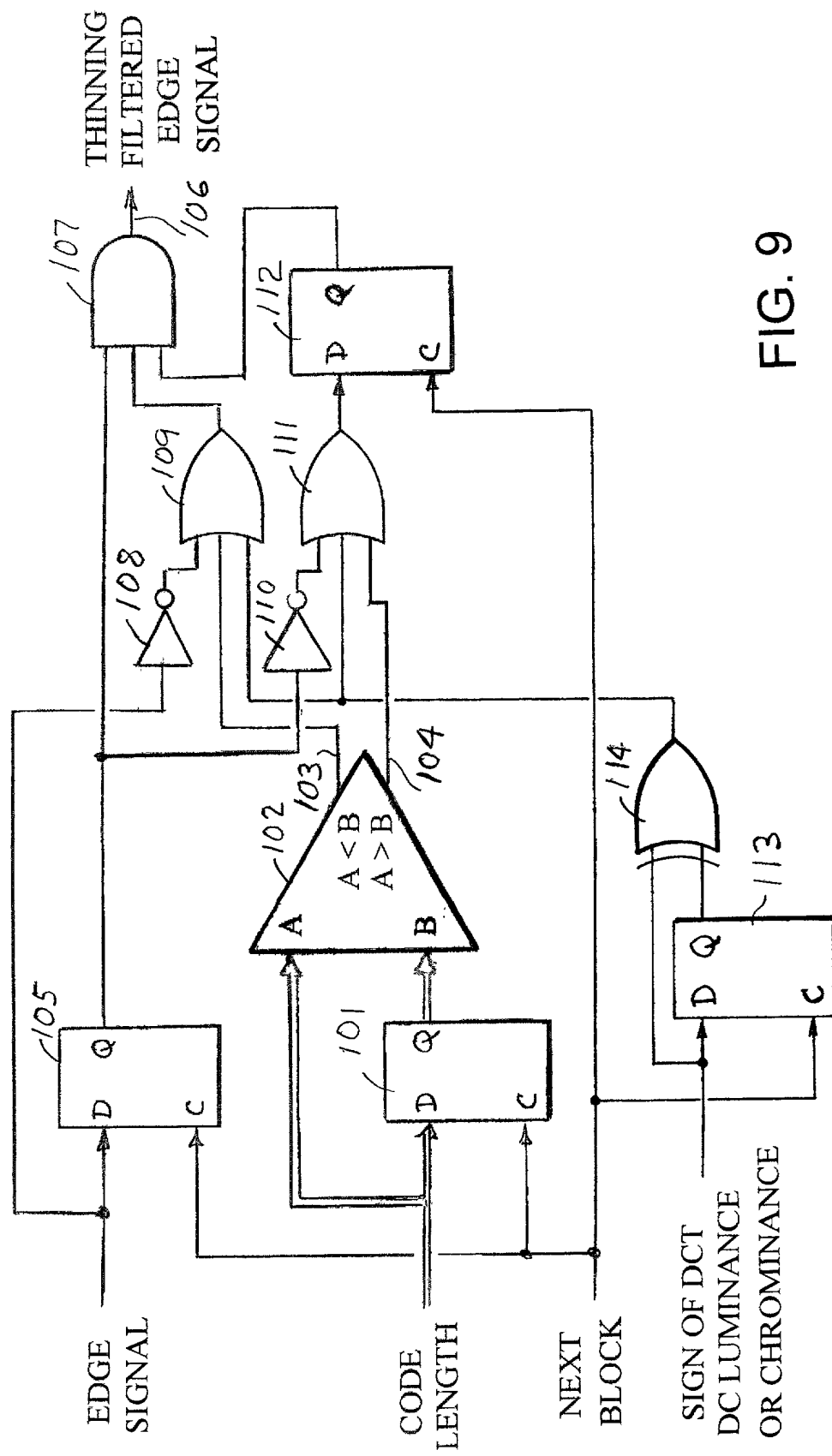


FIG. 9

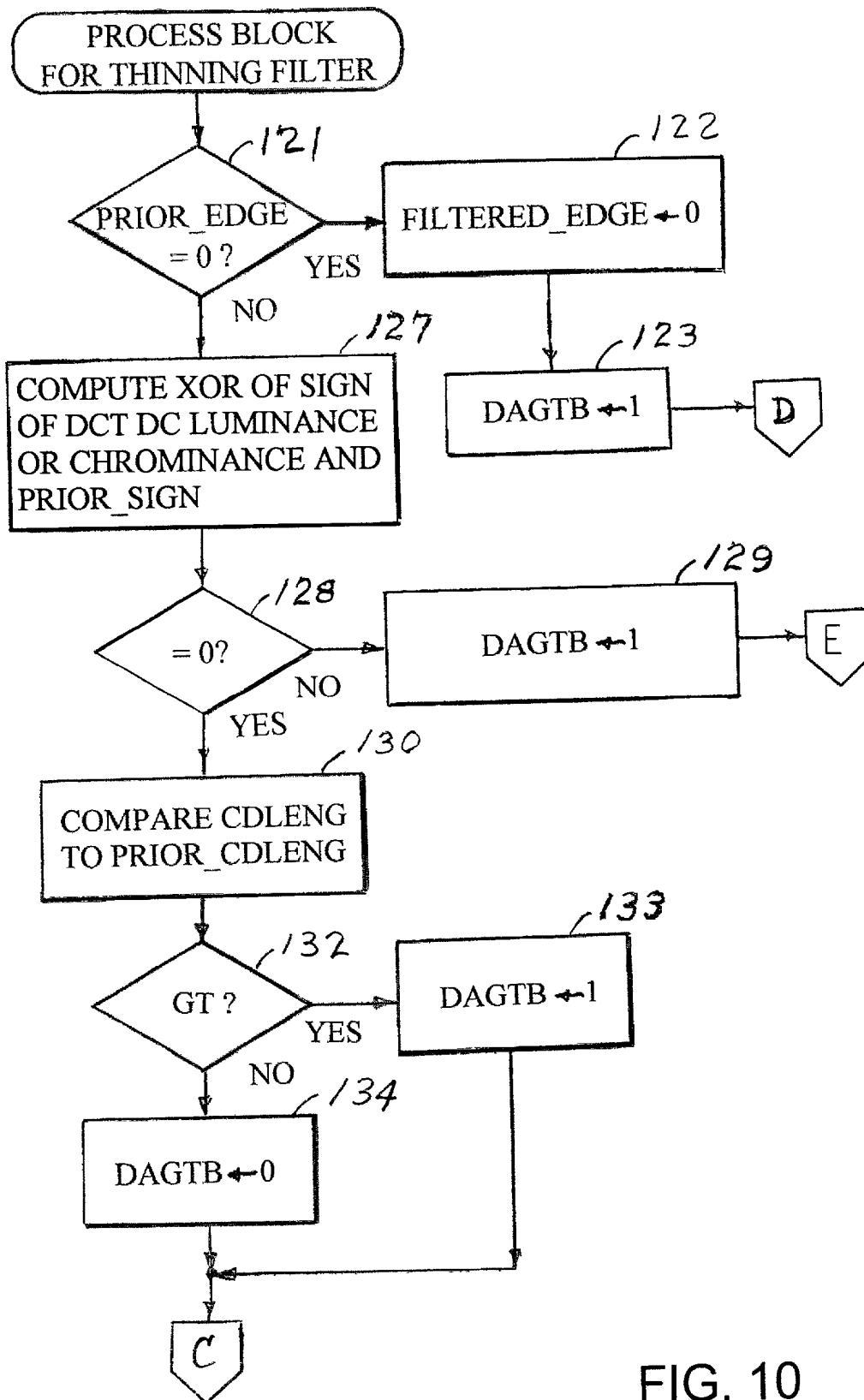


FIG. 10

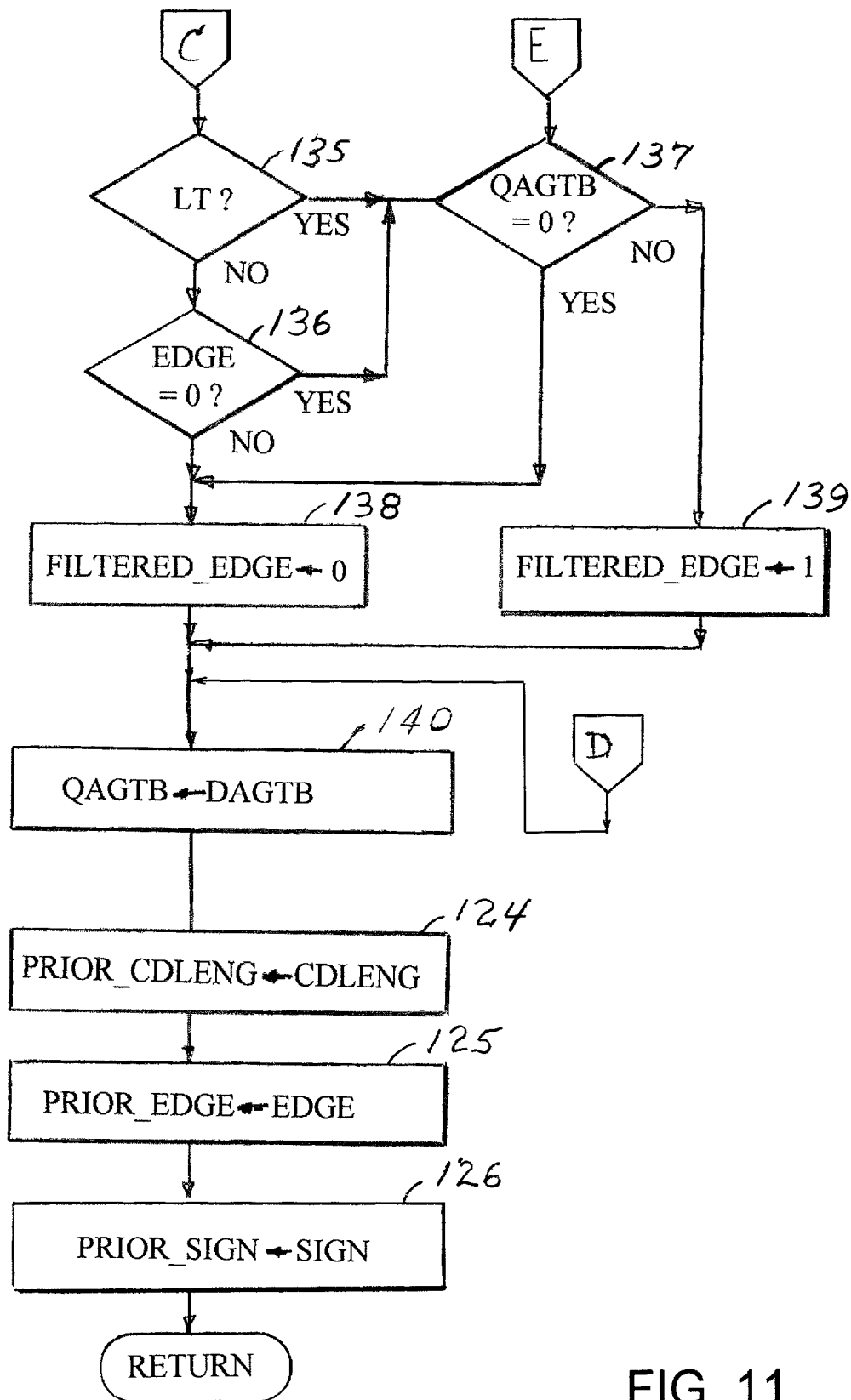


FIG. 11

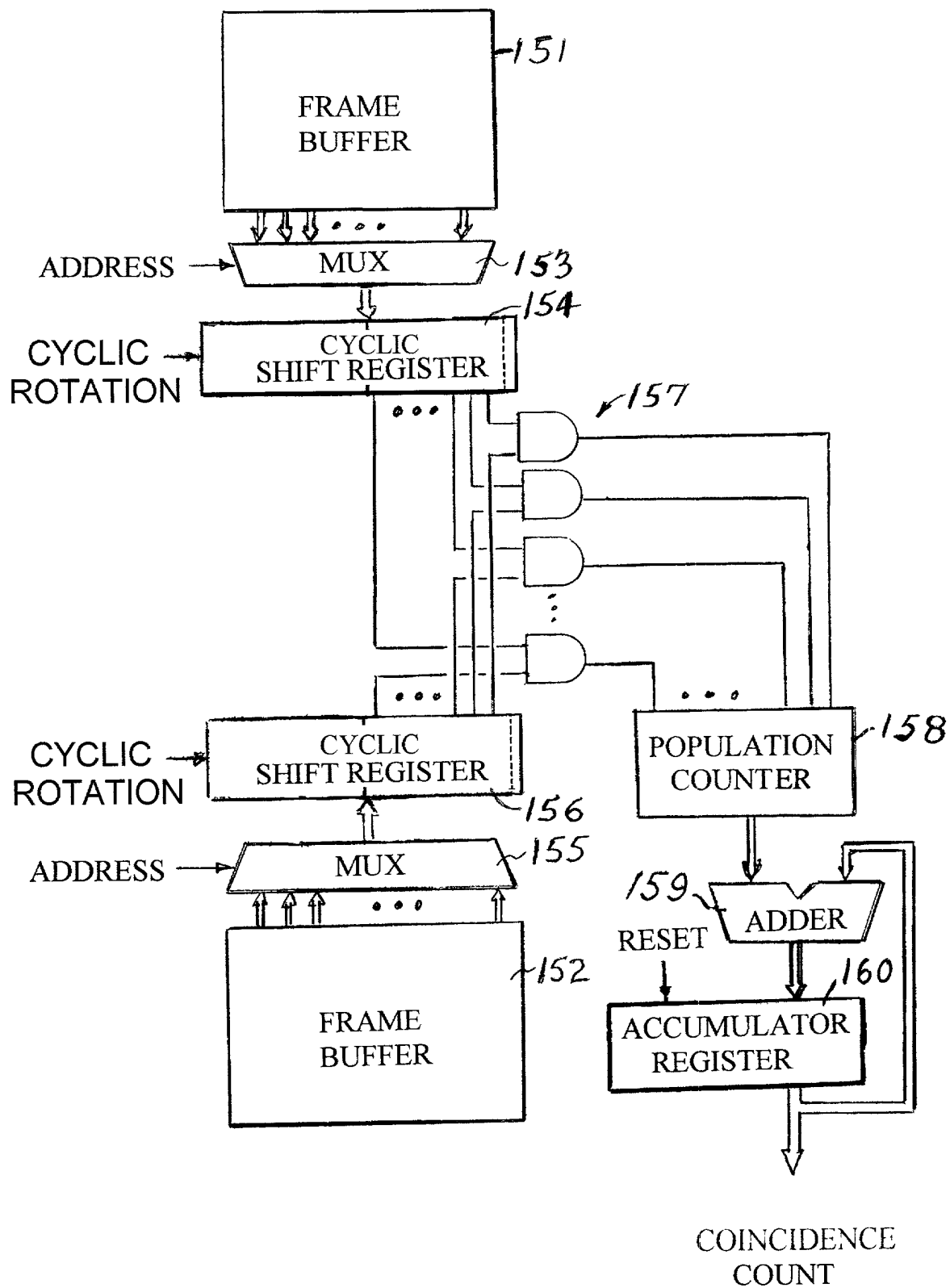


FIG. 12

AUTO-COINCIDENCE MATRIX
COMPARISON

COMPUTE AUTO-COINCIDENCE MATRIX
 $C_c(M,N)$ FOR CURRENT FRAME

COMPUTE COEFFICIENT OF VARIANCE
BETWEEN THE AUTO-COINCIDENCE MATRIX
FOR THE CURRENT FRAME AND THE AUTO-
COINCIDENCE MATRIX FOR THE PRIOR FRAME

$$R_c = \frac{2 \sum_{m,n} (C_c(m,n) - C_p(m,n))^2}{\sum_{m,n} (C_c(m,n)^2 + C_p(m,n)^2)}$$

SAVE THE AUTO-COINCIDENCE MATRIX OF
THE CURRENT FRAME AS THE AUTO-
COINCIDENCE MATRIX FOR THE PRIOR
FRAME TO BE USED WHEN PROCESSING
THE NEXT FRAME

COMPARE THE COEFFICIENT OF VARIANCE
BETWEEN THE AUTO-COINCIDENCE MATRICES
TO A THRESHOLD TO DETECT A SCENE CHANGE

END

FIG. 13

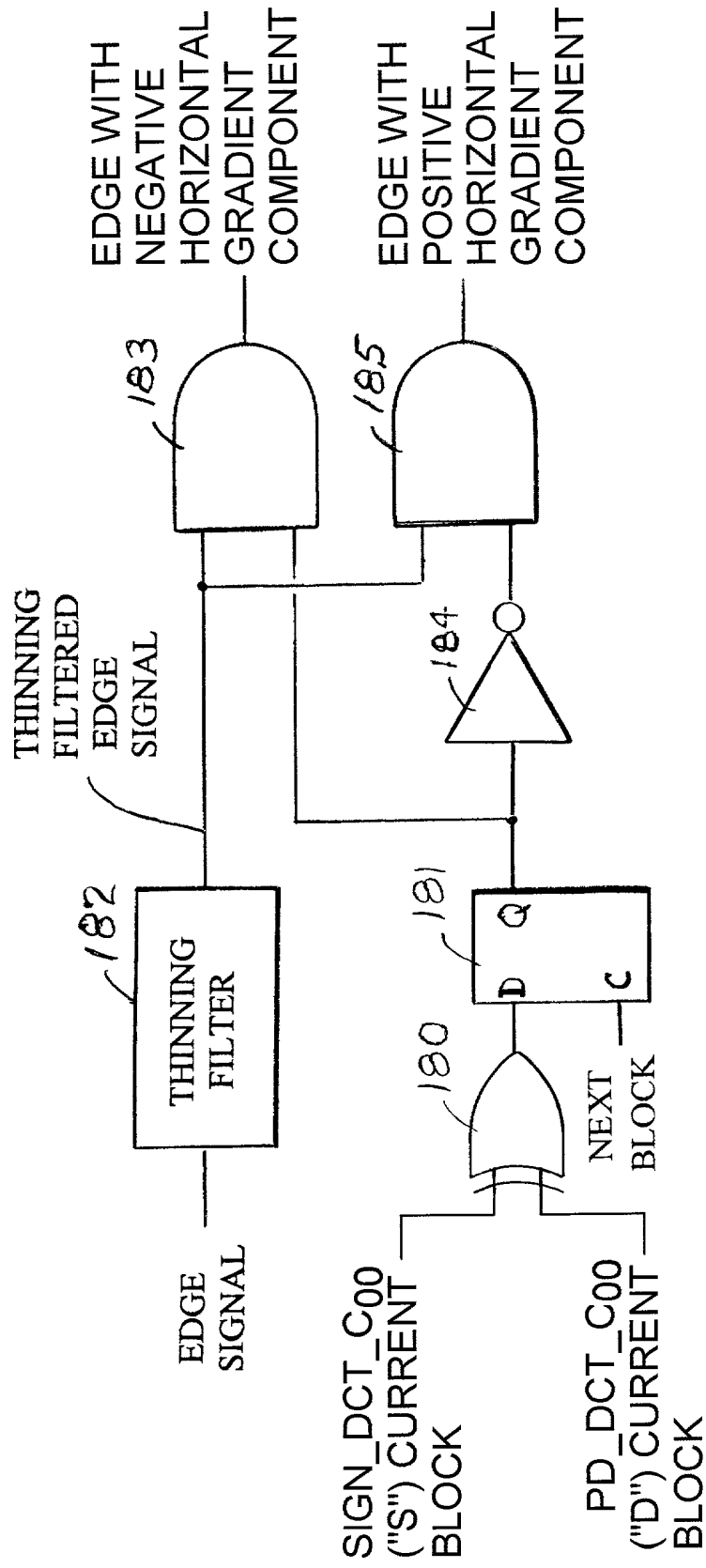


FIG. 14

(4:2:0) CHROMINANCE (Cb AND Cr)

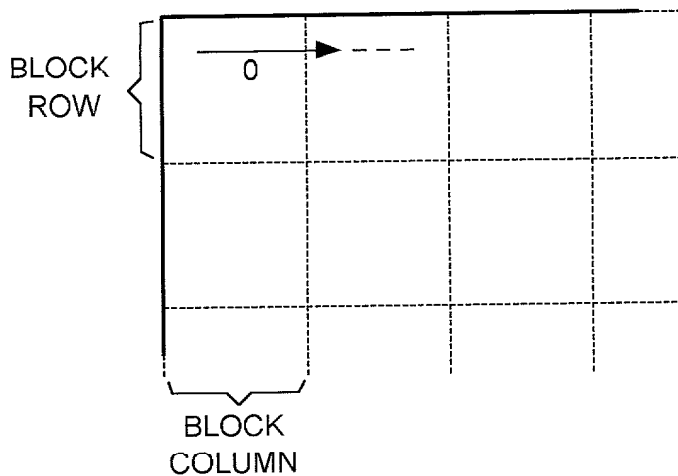


FIG. 15

(4:2:2) CHROMINANCE (Cb AND Cr)

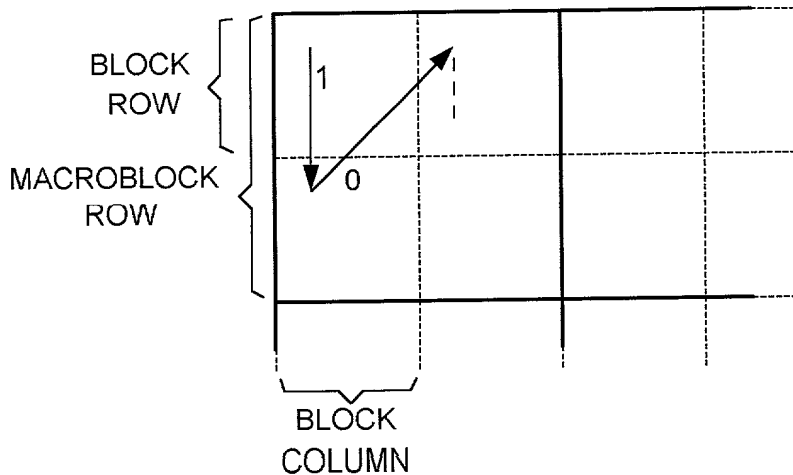


FIG. 16

(4:4:4, 4:2:2, AND 4:2:0) LUMINANCE AND
(4:4:4) CHROMINANCE (Cb AND Cr)

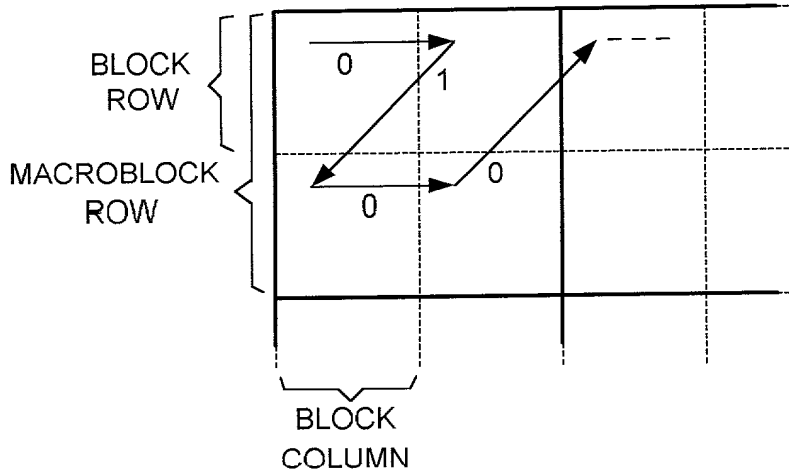


FIG. 17

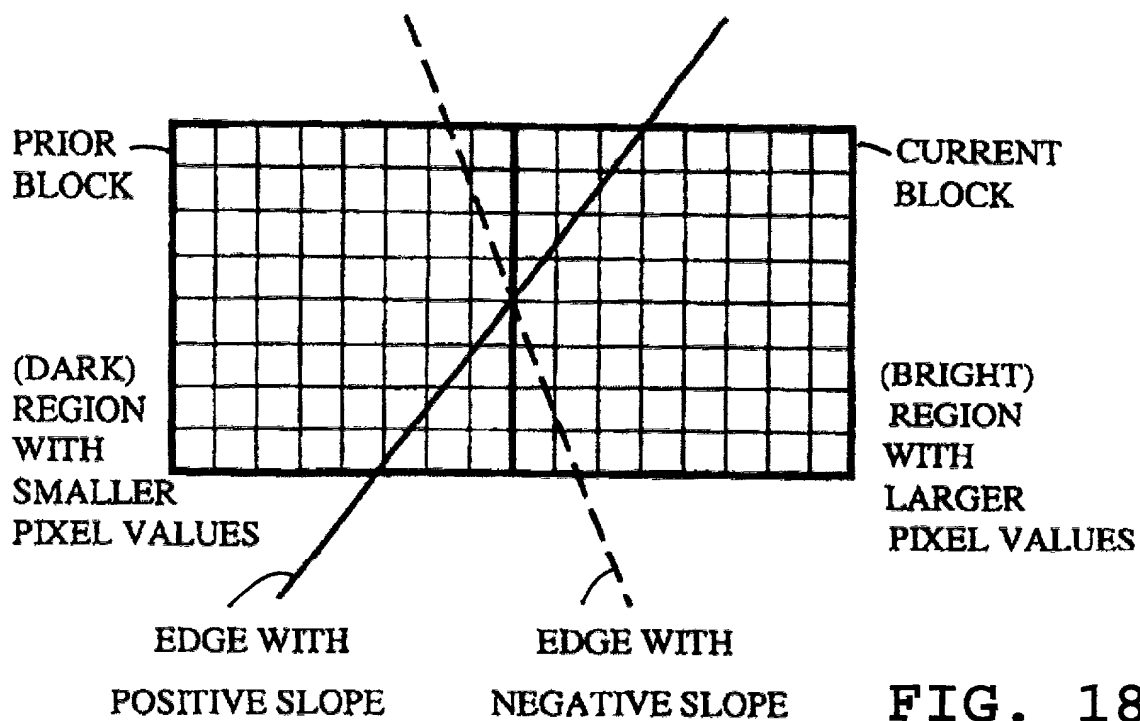


FIG. 18

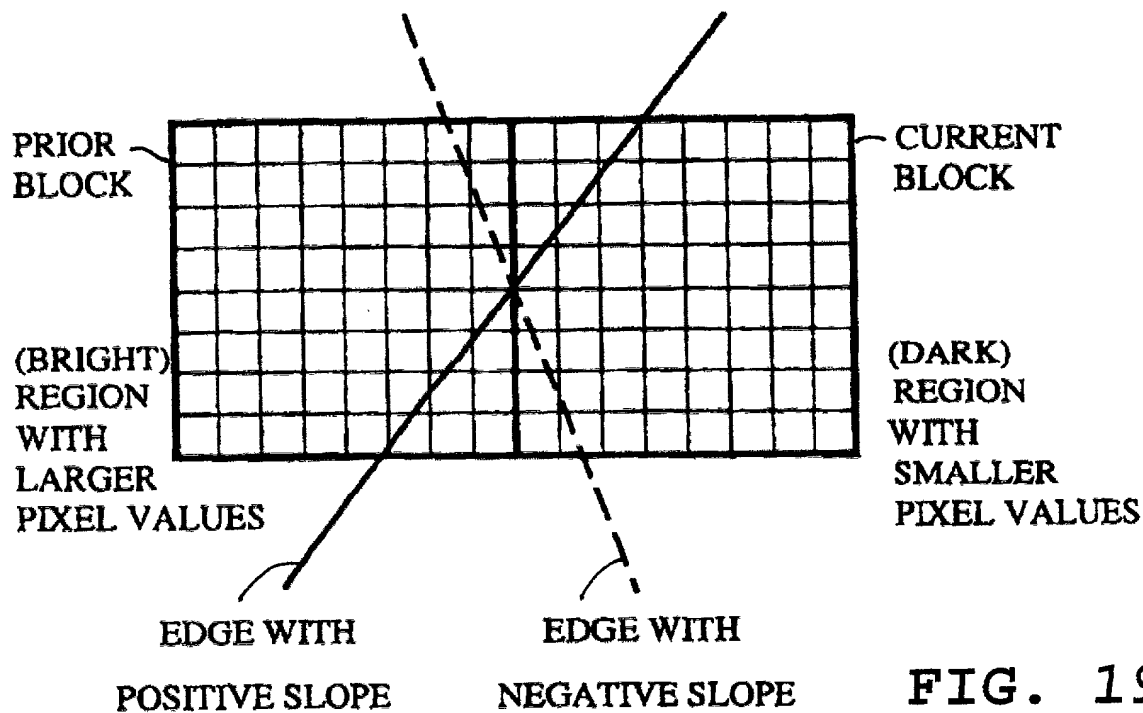


FIG. 19

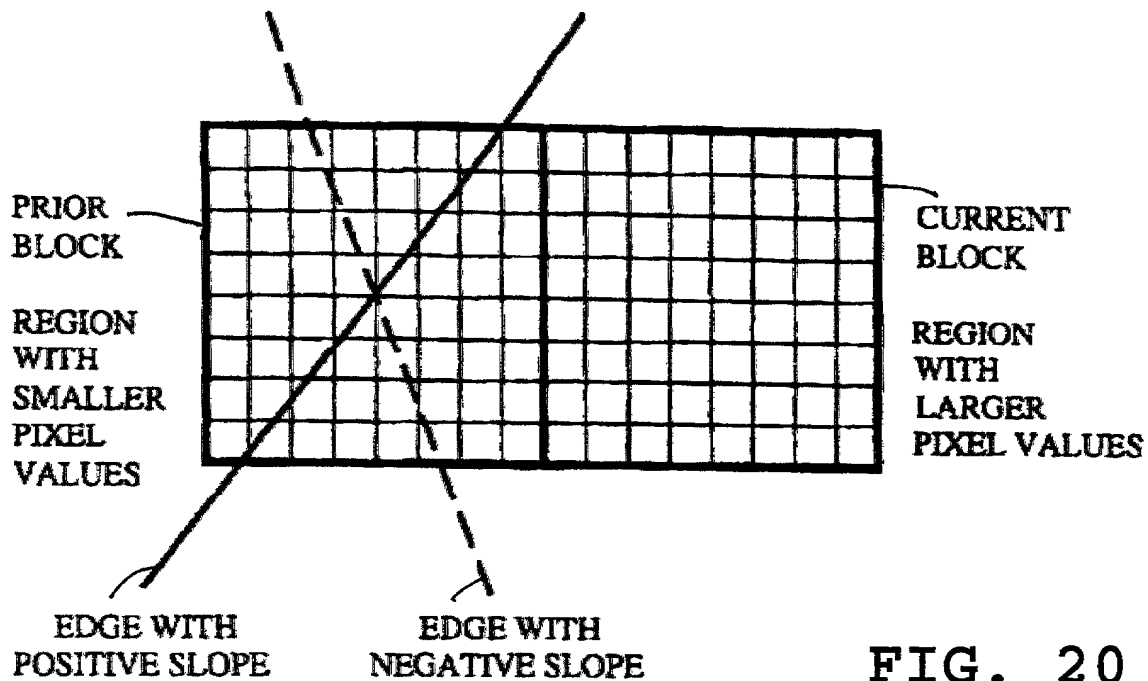


FIG. 20

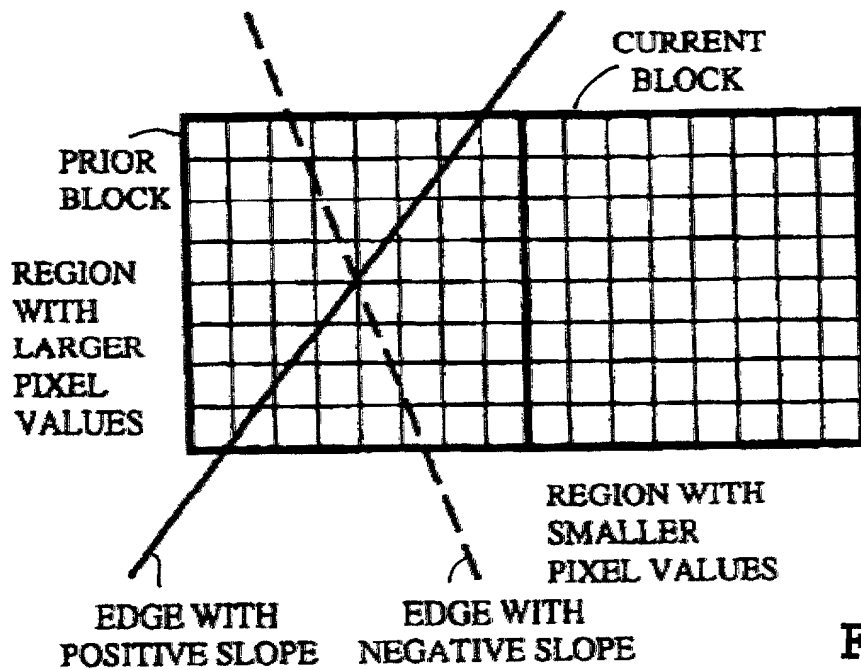


FIG. 21

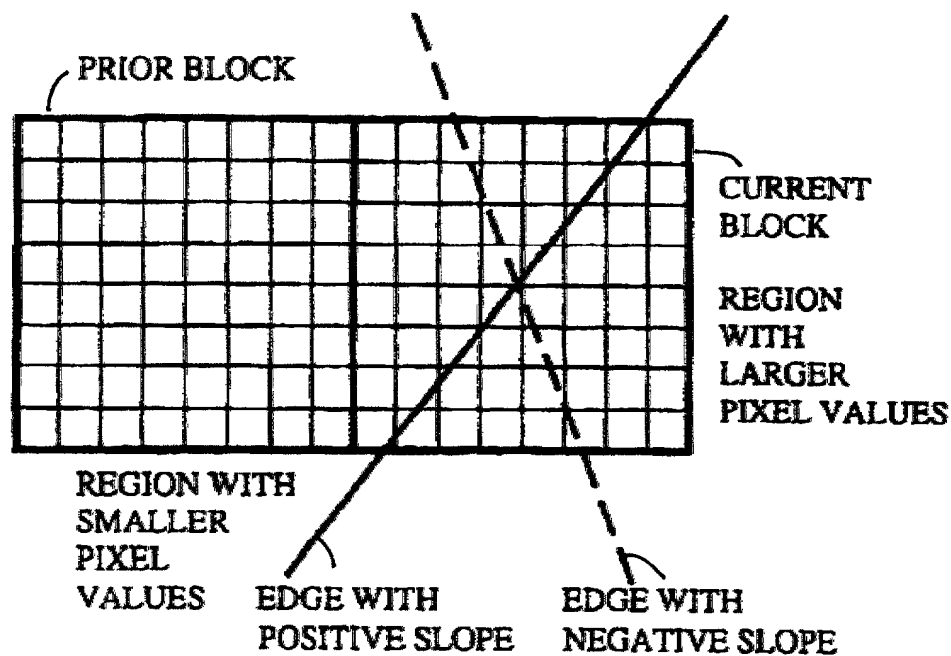


FIG. 22

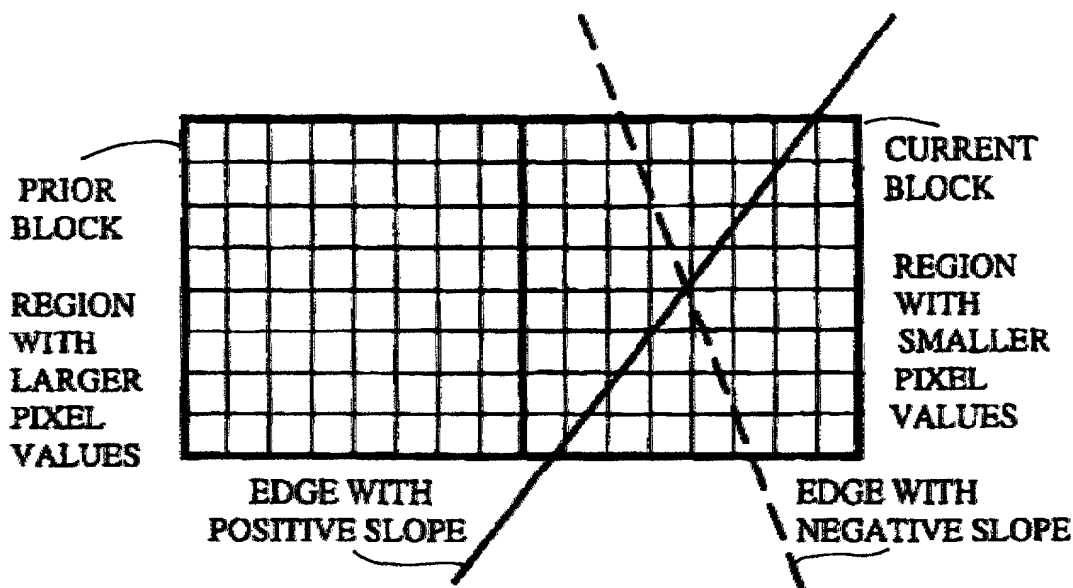


FIG. 23

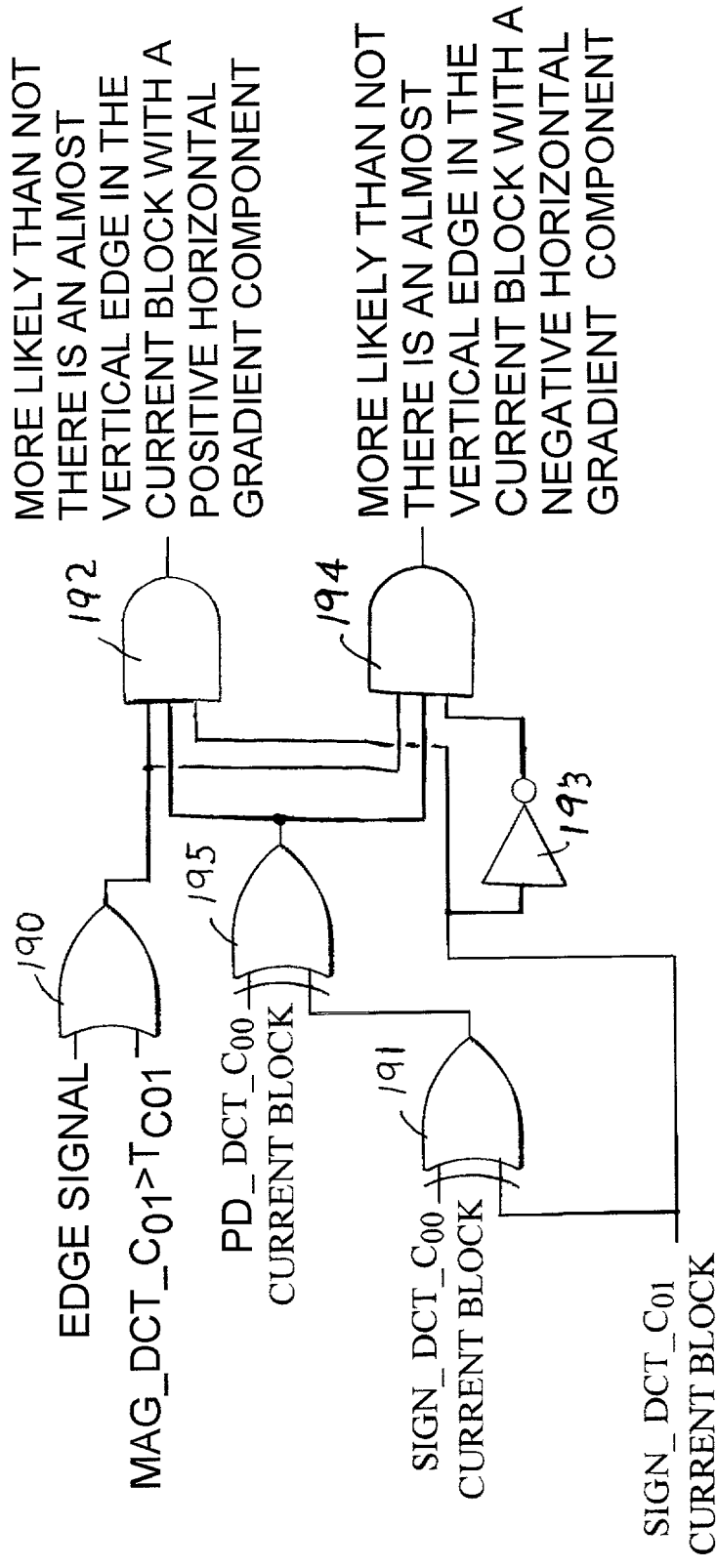


FIG. 24

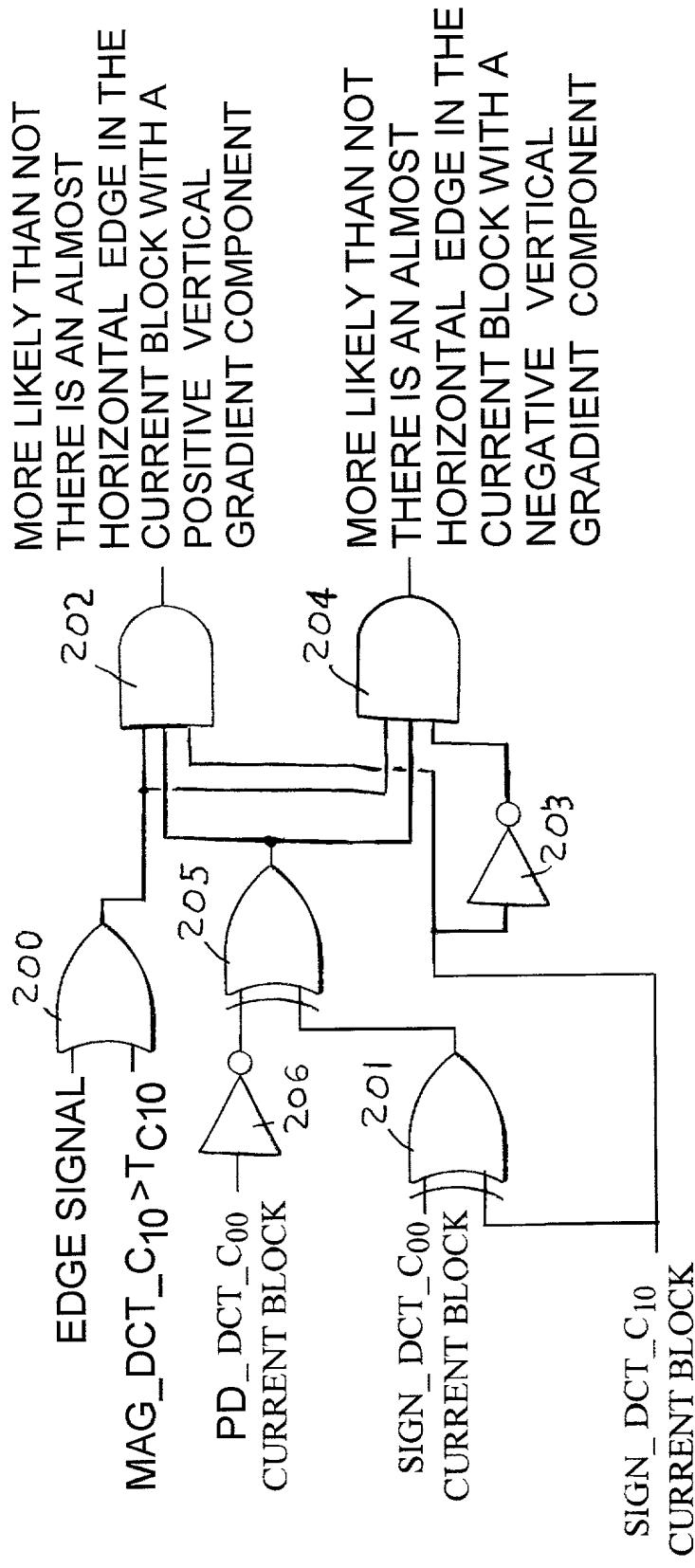


FIG. 25

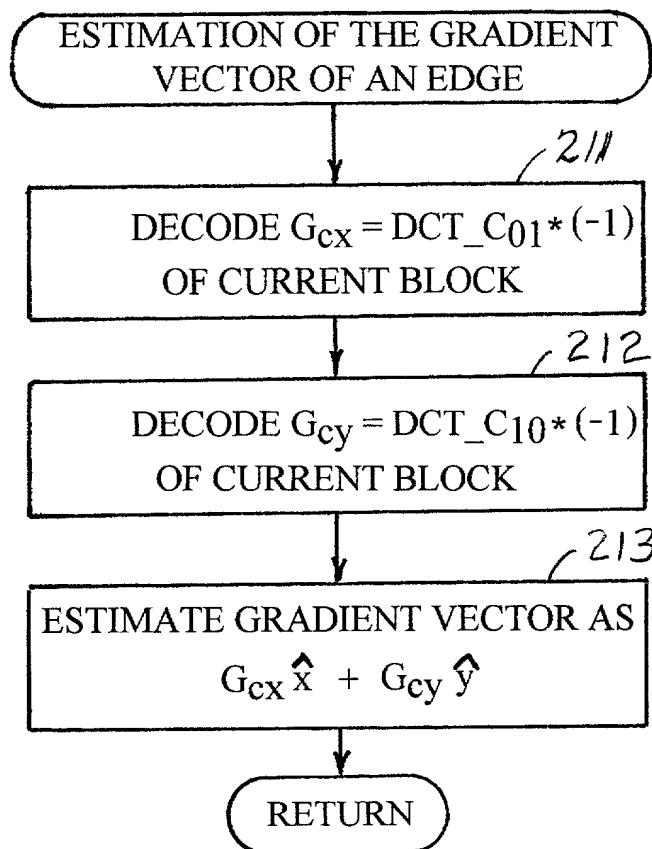


FIG. 26